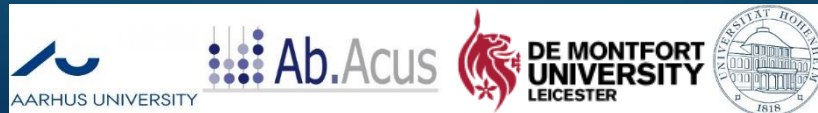


# ROBOT EXPERT PANEL (REP I)

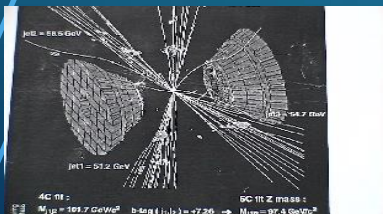
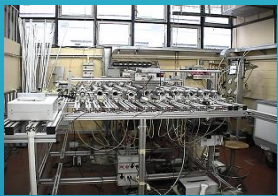


# RESPONSIBLE ETHICAL LEARNING WITH ROBOTICS



"This project has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 731726"

# • Studying Robots and pervasive technology



# REELER introduction

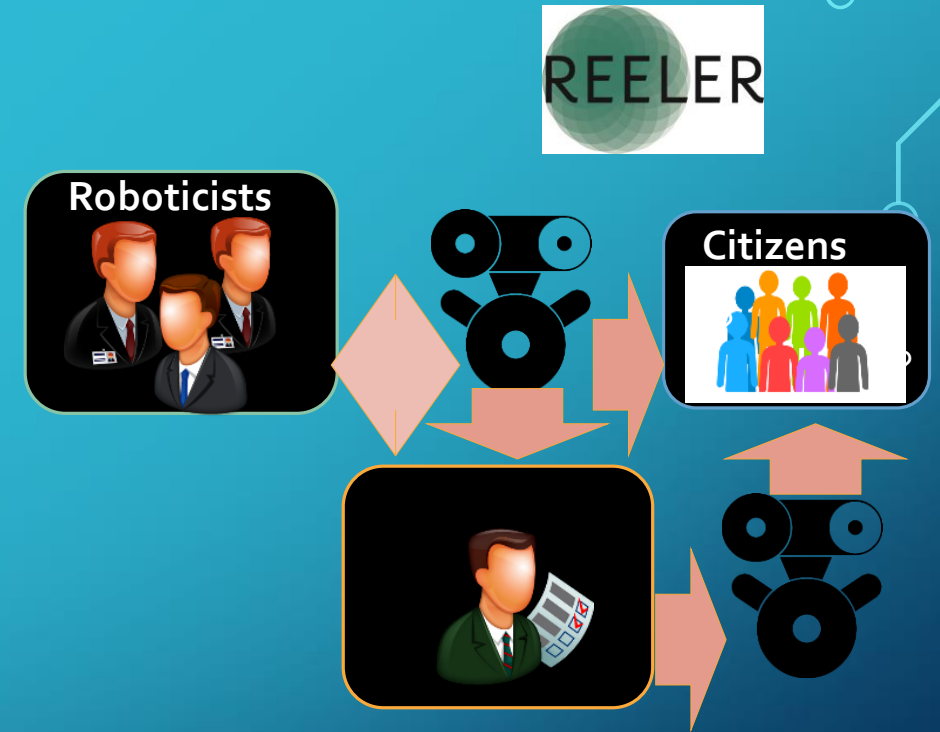
## Motivation:

Distance between

ROBOTICISTS  $\neq$  CITIZENS  $\neq$  POLICY-MAKERS

causes:

- little collaborative learning between groups
- conflicting systems of values
- unintended impact:
  - Not full potential of robots
  - robot sabotage (MIT Technology review, 2015)
  - skewed labour market (Ford, 2015, The Rise of Robots)
  - altered human condition (Floridi (Ed.), 2015, The Onlife Manifesto.)



# Ambition



## REELER seeks to:

1. Align roboticists' visions of a future with robots with empirically-based knowledge of human needs and societal concerns.
2. Develop a proximity-based human-machine ethics that considers how individuals and communities connect with robot technologies.
3. Increase collaboration and unleash learning potential

# REELER – HUMAN ROBOT PROXIMITY SPECTRUM

(ROBOTS EXEMPLIFY THE CASE)



Retrainer  
Ab.Acus



KASPAR  
University of  
Hertfordshire



LBR iiwa  
Kuka



EZ-10  
Easy Mile  
Robosoft



Apple Gripper  
Festo



B-Droid  
Warsaw University of  
Technology



Smart Platform  
Ocado

**HIGHER**  
Integrated

Social

Cooperative

Operative

Parallel

Minimal

**LOWER**  
(None)

Worn or  
implanted on  
a person

Interacts  
socially with  
a person

Cooperates  
physically or  
socially with a  
person

Operated or  
commanded by  
a person

Works  
independently  
alongside a  
person

Independent,  
unlikely to  
contact a  
person

Protected from  
contact with a  
person



# Methodology

- Ethnographic fieldwork among roboticists and affected stakeholders to explore value systems on a case study basis
- Socio-dramas to bring new perspectives to the SSH and robot community
- Mini-Publics to engage citizens in robot developments





# CASE STUDY APPROACH

A semi-structured approach that gives rich data on specific contextualized issues, especially fit for ethnographic work.

Not meant to be representative, but to unfold variation and complexity and to achieve in-depth knowledge of local context.

An explorative and cumulative approach.












# THE VARIATION APPROACH

## Aim:

- Seeking variation in 10-16 cases
- Call forth ethical issues across variation

## Classifications of robots:

- By type
- By functions
- By other?

|   |  |  |
|---|--|--|
|  <p><b>Agriculture</b><br/><i>show Subcategories (7)</i></p>     |  <p><b>Collaborative Robots</b><br/><i>show Subcategories (1)</i></p> |  <p><b>Consumer</b><br/><i>show Subcategories (15)</i></p>  |
|  <p><b>Healthcare</b><br/><i>show Subcategories (9)</i></p>    |  <p><b>Industrial</b><br/><i>show Subcategories (53)</i></p>        |  <p><b>Military</b><br/><i>show Subcategories (7)</i></p> |
|  <p><b>Professional</b><br/><i>show Subcategories (14)</i></p> |  <p><b>Research</b><br/><i>show Subcategories (15)</i></p>          |  <p><b>Space</b><br/><i>show Subcategories (5)</i></p>    |





# Initial approach to the field

Case selection based on robot mapping and seeking variation in:

**Geography;** national heavy and light involvement in robotics (robot-developers/ robot user countries)

**Type of robot;** industrial, agricultural, social, service

**Function/application;**

**Sector;** health, education, industry, service,

**Human proximity;** physically, mentally and socially, effect on wider community

**Technological readiness level**



# ROBOT MAPPING

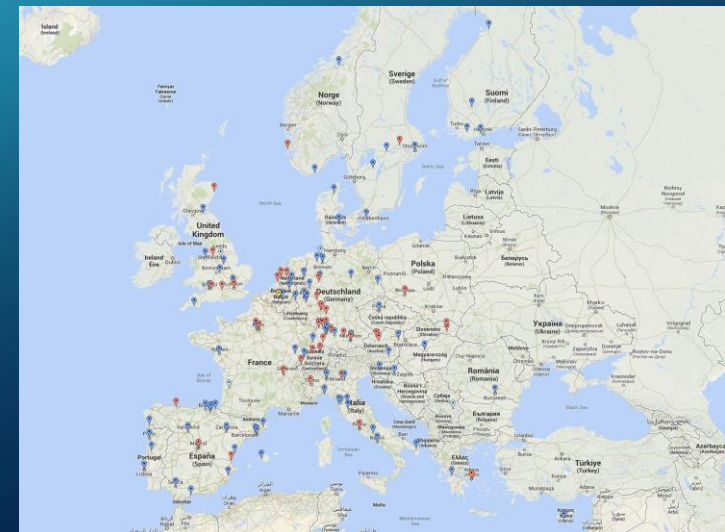
State of Robotics:

Of over 250 euRobotics members, 52 are German organizations, indicating that Germany is invested in SPARC, Horizon2020, and the field of robotics under the EU.

Among Robotics Today's 200 members, 47 are German companies, indicating that Germany is also highly involved in the private robotics community.

Thus far, we have mapped all of the euRobotics members and have begun to map the Robotics Today members.

Stuttgart is a main 'hub'





# Expected impact

Involve affected stakeholders in design processes already in the idea-generation phases through collaborative learning between social scientists and robot designers.

Make robots more ethical and relevant for humans and society.



# REELER ROADMAP

The main outcome of REELER is a research-based roadmap presenting:

- a) ethical guidelines for Human Proximity Levels,
- b) prescriptions for how to include the voice of new types of users and affected stakeholders through Mini-Publics,
- c) calling forth assumptions in robotics through socio-drama
- d) agent-based simulations of the REELER research for policymaking.



# FEEDBACK ON EMPIRICAL RESEARCH

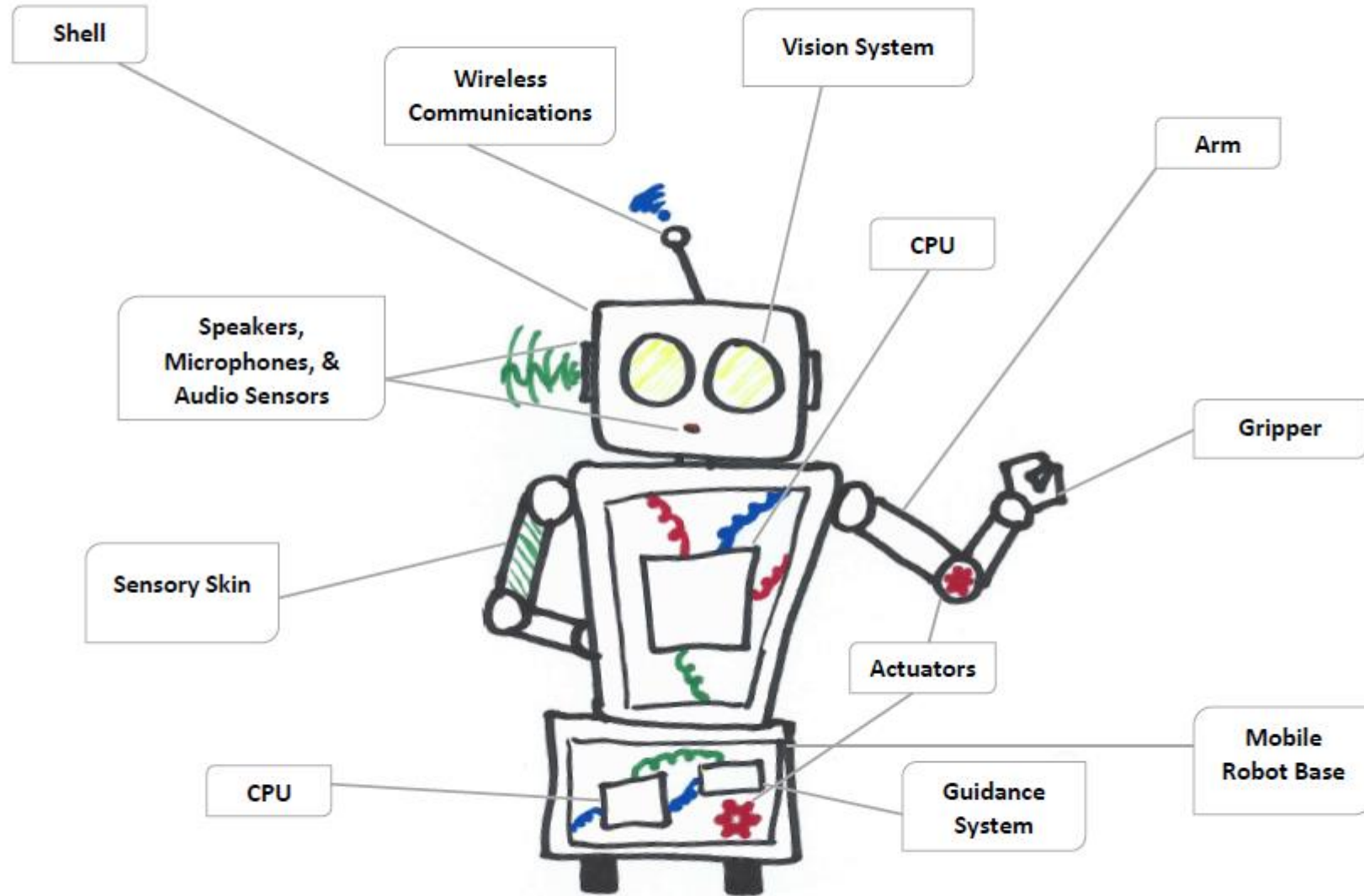
Initial finding:

Robots are highly distributed technologies, and thus implies highly distributed ethical responsibility.

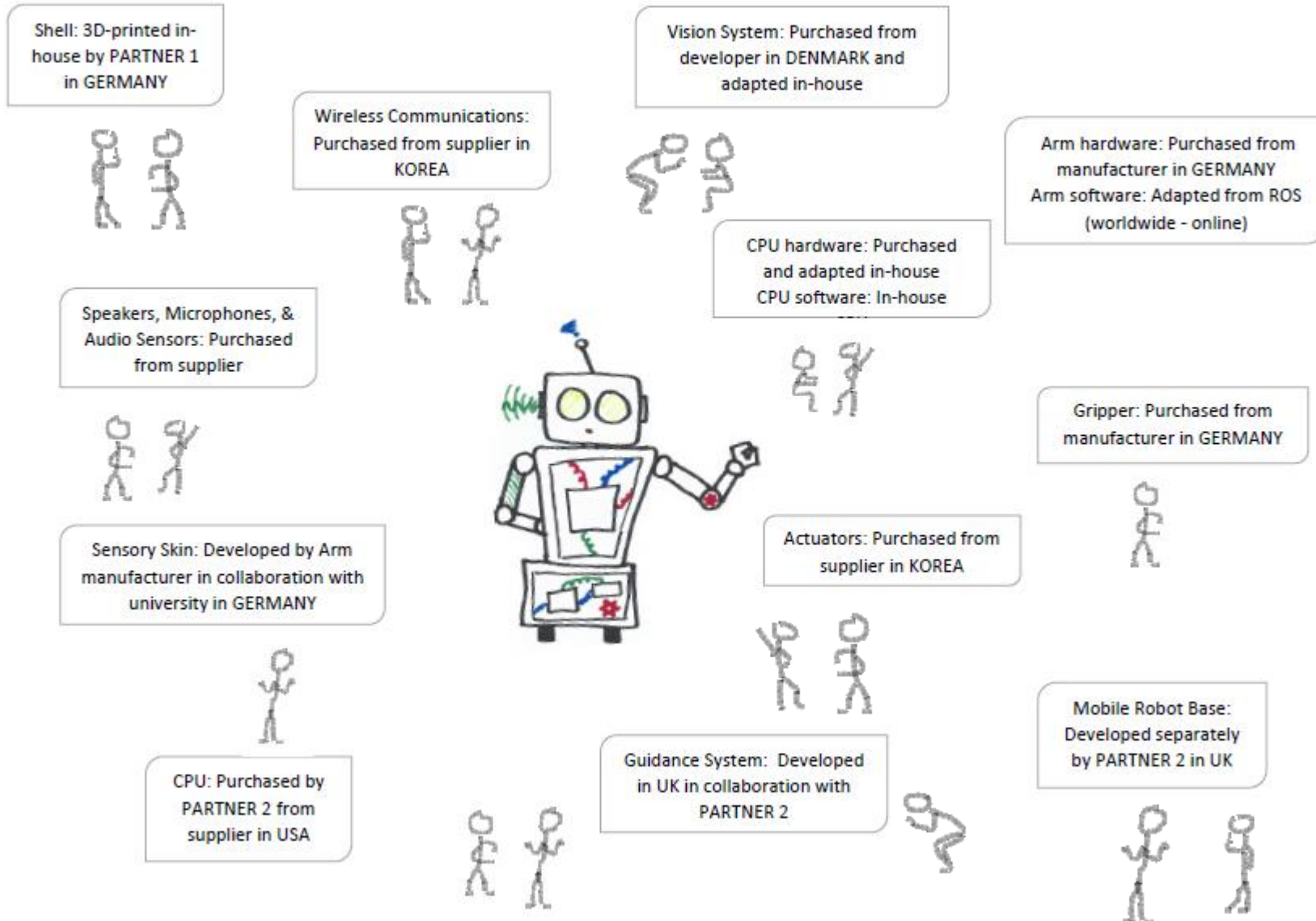
Question:

What is the implication of highly distributed ethical responsibility, seen from a roboticist perspective?

# The robot is a distributed technology



# Where is ethical responsibility in a distributed technology?



# When do ethics come into question?

At conception?



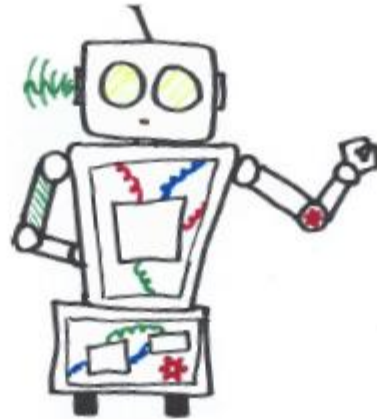
Software development?

0101101

Prototyping?



Applied research?



When it goes to market?



Application and integration?



After a problem arises from use?



# Who is liable when something goes wrong?

Manufacturers or suppliers of components?



Robot developer?

University researchers?



Institution which sold and implemented the robot?



Institution which purchased the robot?



Professional users?



Consumer users?





# SOCIODRAMA

- Sociodrama born out of Psychodrama is a trilogy of *Drama* (the imaginative exploration of the human condition), *Socio* (the interrelatedness of humans and their environments) and *Psychotherapy* (a reflective process of exploring a person's life story).



# SOCIODRAMA

- Sociodrama that emerged from *psychodrama* psychotherapy practice (Moreno 1932).
- Sociodrama helps groups work in an engaged creative and spontaneous explorations of wider cultural and philosophical issues and themes, such as those being examined in the research.



# SOCIODRAMA

- In the action through Sociodrama we can learn to speak as the other in a dialogical encounter with them, whether they be a person, a moral, a robot or ethical question.



## CASES AS SOCIODRAMA

- We want to use *Sociodrama's* extraordinary potential to explore an issue from multiple perspectives without the constraint of reality to enable a deepening of understanding each other and the questions being examined in action.



# THE EXPLORATIVE PROCESS

## OF SOCIAL DRAMA / ROLE-PLAY

- The theme or question selection: the protagonist selection
- **The warm up**
- Grouping: pairing robots and themes
- **The action**
- **The sharing**
- **Processing**



# SOCIAL DRAMA / ROLE-PLAY

- Think about what discussion you will invite us into
- Dramatise 'your' joint themes (e.g. Flobot, Communication and Learning, etc)
- Present your drama
- Engage in a dialogue where your topics are the protagonists and you are these protagonists while we – the audience - ask questions